Asymptotically geodesic surfaces

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ABSTRACT. A sequence of distinct closed surfaces in a hyperbolic 3-manifold *M* is asymptotically geodesic if their principal curvatures tend uniformly to zero. When *M* has finite volume, we show such sequences are always asymptotically dense in the 2-plane Grassmann bundle of *M*. When *M* has infinite volume and is geometrically finite, we show such sequences do not exist. As an application of the former, we obtain partial answers to the question of whether a negatively curved Riemannian 3-manifold that contains a sequence of asymptotically totally geodesic or totally umbilic surfaces must be hyperbolic. Finally, we give examples to show that if the dimension of *M* is greater than 3, the possible limiting behavior of asymptotically geodesic surfaces is less constrained than for totally geodesic surfaces.

1. Introduction

A sequence of distinct connected closed surfaces in a hyperbolic 3-manifold M is asymptotically geodesic if their principal curvatures tend to zero in L^{∞} norm. Kahn-Marković and Kahn-Wright showed that when M has finite volume, such sequences of surfaces exist abundantly [KM12b], [KW21]. The first theorem (Theorem 1.1) in this article implies that such sequences (S_n) of surfaces are always asymptotically dense in the 2-plane Grassmann bundle Gr M of M – given an open $B \subset Gr M$, there is N so for every $n \geq N$, S_n intersects B. This result is used to obtain partial answers to variations on the question of whether a closed negatively curved Riemannian manifold that contains a sequence of asymptotically geodesic surfaces is hyperbolic (Theorems 1.7, 1.10.)

We also show (Theorem 1.6) that sequences of distinct asymptotically geodesic surfaces do not exist in geometrically finite hyperbolic 3-manifolds M of *infinite volume*. Precisely, we show there is $\epsilon(M) > 0$ so that a closed surface of principal curvatures smaller than ϵ in absolute value is homotopic to a totally geodesic surface.

There can be real qualitative differences in the behavior of sequences of totally geodesic surfaces and sequences of surfaces that are only asymptotically geodesic. For example, the first author showed that a sequence of distinct asymptotically geodesic surfaces Σ_n in a hyperbolic 3-manifold can scar along a closed totally geodesic surface Σ , in the sense that the corresponding sequence of probability measures ν_{Σ_n} converges to the probability measure corresponding to Σ [AA]. This is in contrast to what happens for sequences of distinct closed totally geodesic Σ_n in M, which Mozes-Shah showed must become uniformly distributed [MS95].

1

Most of our theorems are in the opposite direction, and show that asymptotically geodesic surfaces in negative curvature enjoy many of the same rigidity properties as totally geodesic surfaces. In fact, many of our proofs rely on theorems from homogeneous dynamics that establish those rigidity properties for totally geodesic surfaces, such as the fact proven by Ratner and Shah that they are either closed or dense in a hyperbolic 3-manifold of finite volume [Rat91],[Sha91].

On the other hand, we construct sequences of asymptotically Fuchsian (K_n -quasifuchsian for $K_n \to 1$) pleated surfaces and minimal surfaces in certain hyperbolic d-manifolds M with $d \ge 4$ whose Hausdorff limit is a union of two distinct totally geodesic submanifold of M (Theorem 1.5.) This contrasts with the fact, that follows from the work of Mozes-Shah, that the Hausdorff limit of a sequence of totally geodesic surfaces in M, if it exists, has to be a single totally geodesic k-submanifold for $3 \le k \le d$ (Proposition 5.2.)

1.1. **Density of asymptotically geodesic surfaces in finite volume.** Let $M = \Gamma \backslash \mathbf{H}^3$ be a hyperbolic 3-manifold of finite volume, where $\Gamma \leq \mathrm{PSL}_2 \, \mathbf{C}$ is a lattice. All surfaces in this paper will be connected. An essential surface $S \subset M$ is K-quasifuchsian if $\pi_1(S) \leq \pi_1 M = \Gamma$ is a K-quasifuchsian subgroup of $\mathrm{PSL}_2 \, \mathbf{C}$, i.e., there is a K-quasiconformal homeomorphism $\phi: \partial_\infty \mathbf{H}^3 \to \partial_\infty \mathbf{H}^3$ so $\phi \circ \pi_1(S) \circ \phi^{-1}$ is Fuchsian. For K sufficiently close to 1, work by Uhlenbeck and Seppi imply that K-quasifuchsian surfaces $S \subset M$ are homotopic to unique minimal surfaces with principal curvatures going to zero uniformly as $K \to 1$ [Uhl83],[Sep16]. Our first theorem is:

Theorem 1.1. Let M be a finite volume hyperbolic 3-manifold. Let B be an open set. Then, there is $\epsilon = \epsilon(B) > 0$ such that all $(1 + \epsilon)$ -quasifuchsian minimal surfaces in M that are not totally geodesic meet B.

As direct consequences of the previous theorem (and its proof), we obtain the following two corollaries. We say that a surface S is ϵ -dense in GrM if every tangent 2-plane to M is at a distance of at most ϵ from some tangent plane to S.

Corollary 1.2. For every $\epsilon > 0$ there is some $\eta = \eta(M) > 0$ so that all but finitely many $(1 + \eta)$ -quasifuchsian closed minimal surfaces are ϵ -dense in the Grassmann bundle of tangent 2-planes to the η -thick part of M. Moreover, the ones which are not are totally geodesic.

Corollary 1.3. Let (S_n) be a sequence of distinct closed asymptotically Fuchsian minimal surfaces in M. Then, (S_n) is asymptotically dense in Gr M: for every open $U \subset Gr$ M, there is N so that for every $n \ge N$, S_n intersects U.

These theorems imply that, in the topology induced by the Hausdorff distance between closed sets in Gr M, sequences of asymptotically geodesic surfaces S_n always limit to all of Gr M. This is in contrast with the fact that sequences of asymptotically geodesic surfaces S_n may not equidistribute in Gr M – in fact, work by the first author showed that the

probability measures v_n induced by them on GrM may limit in the weak-* topology to a measure supported on a single totally geodesic surface in M [AA].

A crucial ingredient in these proofs is the Ratner-Shah theorem stating that totally geodesic surfaces are either closed or dense in M. When M has infinitely many distinct totally geodesic surfaces, the fact due to Mozes-Shah that they are equidistributing also plays an important role [MS95].

Remark 1.4. Results similar to the previous theorem and corollaries were recently and independently obtained by Xiaolong Hans Han [Han25].

1.2. **Hausdorff limits in higher dimensions.** We say a sequence of surfaces (S_n) in a hyperbolic d-manifold M is asymptotically Fuchsian if the S_n are K_n -quasifuchsian for $K_n \to 1$ as $n \to \infty$. (Analogously to the 3-dimensional case, we say an essential surface $S \subset M$ is K-quasifuchsian if $\pi_1(S) \leq SO(d,1)$ is a K-quasifuchsian subgroup, meaning there is a K-quasiconformal homeomorphism of $\partial_\infty \mathbf{H}^d$ conjugating $\pi_1(S)$ into SO(2,1).)

Asymptotically Fuchsian surfaces in *M* are always homotopic to asymptotically geodesic ones [Jia21]. Conversely, asymptotically geodesic surfaces are asymptotically Fuchsian [Eps86]. We show

Theorem 1.5. Suppose M is a closed hyperbolic d-manifold containing two closed totally geodesic 3-dimensional submanifolds N_1 and N_2 that intersect along a closed totally geodesic surface.

Then, there exists a sequence (S_n) of asymptotically Fuchsian closed connected pleated surfaces whose Hausdorff limit in M is $N_1 \cup N_2$. There also exists a sequence (S_n) of asymptotically geodesic minimal surfaces whose Hausdorff limit in M is $N_1 \cup N_2$.

This is in contrast with the fact that the Hausdorff limit of a sequence of connected closed *totally geodesic* surfaces in a closed hyperbolic *d*-manifold is always a single totally geodesic submanifold when it exists (see Section 5.2.)

To construct the surfaces (S_n) , we construct sequences (S_n^1) and (S_n^2) of closed, connected, equidistributing surfaces on each of the N_i . These surfaces are built out of *good pants* – pants with large but nearly identical cuff lengths, following Kahn-Marković and Kahn-Wright, as well as Liu-Marković to ensure they are connected. We join the sequences inside each N_i with a surgery and argue they remain asymptotically Fuchsian, using the fact that the totally geodesic surface $N_1 \cap N_2$ has a finite cover built out of the same building blocks as (S_n^1) and (S_n^2) (as shown by Kahn-Marković in their proof of the Ehrenpreis conjecture [KM15]).

1.3. Nonexistence of asymptotically geodesic surfaces in infinite volume. We now let M be a geometrically finite hyperbolic 3-manifold of *infinite volume*. We say a surface $S \subset M$ is *essential* if it is π_1 -injective.

Theorem 1.6. Let M be a geometrically finite hyperbolic 3-manifold of infinite volume. Then, there is $\epsilon = \epsilon(M) > 0$ so that any closed essential surface $S \subset M$ with principal curvatures at most ϵ in absolute value is homotopic to a totally geodesic surface.

Similarly, let $\Gamma < \mathrm{PSL}_2 \, \mathbf{C}$ be a geometrically finite Kleinian group of infinite covolume. There is $\epsilon = \epsilon(\Gamma) > 0$ so that any $(1 + \epsilon)$ -quasifuchsian surface subgroup of Γ is Fuchsian.

Combined with the fact proven by McMullen-Mohammadi-Oh [MMO17] and Benoist-Oh [BO22] that such M only contain finitely many compact totally geodesic sufaces, this shows that M contains no sequences of distinct closed asymptotically geodesic surfaces. This in contrast with the case when M has finite volume, where the theorems of Kahn-Marković and Kahn-Wright show that there are many sequences of closed asymptotically geodesic surfaces.

On the other hand, when M is also acylindrical, Cooper, Long and Reid show M contains infinitely many essential homotopy classes of surfaces that cannot be homotoped to a connected component of the boundary of the convex core and any two of which are geometrically distinct: they cannot be homotoped to the same subspace of M [CLR97]. Theorem 1.6 shows they are not $(1 + \epsilon(\Gamma))$ -quasifuchsian, except for possibly finitely many that are totally geodesic.

When the convex core of M is compact and has totally geodesic boundary, we are able to prove Theorem 1.6 by contradiction – if M had a sequence of closed asymptotically geodesic surfaces, their minimal representatives would all live inside the convex core of M, so they would not be dense in the *double* of M, violating Corollary 1.3. In the general case, we also give an argument by contradiction, but using the theorem of Benoist-Oh (following McMullen-Mohammadi-Oh) that there are only finitely many compact totally geodesic surfaces in the convex core of M.

For M as above, let $\epsilon(M)$ be the supremum over all $\epsilon > 0$ such that $(1 + \epsilon)$ -quasifuchsian essential surfaces of M are Fuchsian. We have shown $\epsilon(M) > 0$, but we can still ask

Question 1. ¹ Is it possible to estimate $\epsilon(M)$ in terms of geometric or topological properties M? Is the infimum of $\epsilon(M)$ positive as M ranges over the deformation space of complete hyperbolic structures on M, minus a neighborhood of the subspace of hyperbolic structures with a Fuchsian end?

As discussed above, finite volume hyperbolic 3-manifolds contain a great many sequences of closed non-totally geodesic hypersurfaces with principal curvatures tending to 0. It is unknown whether finite volume higher dimensional hyperbolic manifolds are more like infinite volume hyperbolic 3-manifolds or finite volume hyperbolic 3-manifolds in this regard.

¹This question was suggested by Alan Reid.

Question 2. Let M be a finite volume hyperbolic d-manifold of dimension $d \ge 4$. Given $\epsilon > 0$, does M contain a closed essential hypersurface with principal curvatures at most ϵ in absolute value that is not homotopic to a totally geodesic hypersurface? Is there any such M that does?

1.4. **Rigidity of asymptotically geodesic surfaces in negative curvature.** We are interested in variations on the following question. Corollary 1.3 will play an important role in the results we obtain.

Question 3. Let (M, g) be a closed negatively curved 3-manifold containing a sequence of distinct asymptotically geodesic surfaces. Must (M, g) have constant curvature?

With a strong topological assumption on the surfaces, we are able to give a positive answer. Recall that by geometrization every closed negatively curved 3-manifold carries a hyperbolic metric, which by Mostow rigidity is unique up to isometry.

Theorem 1.7. Let (M, g) be a closed negatively curved 3-manifold and $(\Sigma_n) \subset (M, g)$ be a sequence of asymptotically geodesic surfaces.

Suppose there is a diffeomorphism $\phi: M \to M$ so that $S_n := \phi(\Sigma_n)$ form a sequence of asymptotically geodesic surfaces for the hyperbolic metric g_{hyp} on M. Then, g is isometric to g_{hyp} .

To prove this, we show that GrM has a dense totally geodesic plane for the metric g, and by a classical result of Cartan we are able to conclude g is hyperbolic. To do so, we use the fact that the surfaces S_n are asymptotically dense in GrM, per Corollary 1.3. We are then able to show that the corresponding surfaces in the metric g are asymptotically dense by following ideas from the article of Calegari-Marques-Neves [CMN22], which proved a rigidity result for negatively curved closed 3-manifolds in terms of the growth rate of essential minimal surfaces, counted by area.

Question 3 is not fully settled even when we assume (M, g) contains a sequence of distinct *totally geodesic* surfaces. In that setting, however, there has been recent progress: Filip-Fisher-Lowe [FFL24] answer it positively when the metric g is analytic, and by the work of Bader-Fisher-Miller-Stover [BFMS21] and Margulis-Mohammadi [MM22], one concludes that (M, g) is in fact an arithmetic hyperbolic manifold.

In all of these works, the fact that the distinct totally geodesic surfaces are asymptotically dense in GrM (in fact, they equidistribute) plays a major role. A natural next question is whether one can obtain rigidity theorems knowing only about finitely many or even a single surface. For example, one can ask whether (M, g) containing a closed sufficiently large geodesic hyperbolic surface is enough to force g to be hyperbolic. Without any additional conditions, it is easy to show there can be no rigidity by perturbing the metric in a small ball. However, imposing an upper bound on the curvature we are able to prove the following theorem.

Theorem 1.8. Let (M, g_{hyp}) be a closed hyperbolic 3-manifold. Then there is $\epsilon > 0$ and a finite collection of closed totally geodesic surfaces so that if S is $(1 + \epsilon)$ -quasifuchsian surface that does not belong to the finite collection of totally geodesic surfaces, the following holds.

Assume g is a metric on M with sectional curvature bounded above by -1 so that

- Σ is a totally geodesic hyperbolic surface in (M, g)
- There is a homotopy equivalence $\phi: M \to M$ so $\phi(\Sigma) = S$.

Then, g is isometric to g_{hyp} and S is homotopic to a totally geodesic surface in (M, g_{hyp}) .

The second author proved this result for all but finitely many totally geodesic surfaces in (M, g_{hyp}) , and building on work by V. Lima gave examples to show that it was necessary to exclude finitely many totally geodesic surfaces [Low23], [Lim19]. By the work described above we can only have infinitely many distinct closed totally geodesic S when M is arithmetic, which is a very strong condition on a hyperbolic 3-manifold. However, every closed hyperbolic 3-manifold contains many sequences of distinct asymptotically geodesic surfaces, from the Kahn-Marković surface subgroup theorem. Therefore by the previous theorem every closed hyperbolic 3-manifold contains many essential surfaces that are not homotopic to totally geodesic hyperbolic surfaces in any metric with sectional curvature at most -1.

The second author's original result was proved by arguing that the surface Σ must be well-distributed, meaning that any point in the universal cover \tilde{M} is enclosed in a cube whose faces are lifts of Σ to \tilde{M} (compare with the notion of a filling surface recently introduced by X.H. Han [Han25].) Then he shows that the existence of a well-distributed surface $\Sigma \subset M$ implies the metric g must be hyperbolic. To show Σ is well-distributed, he uses the fact that the S_k are asymptotically dense in $Gr_2 M$, from the work of Mozes-Shah [MS95]. Corollary 1.3 implies the S_k are asymptotically dense in $Gr_2 M$ even if they are only asymptotically geodesic, so we are able to follow Lowe's original proof and obtain Theorem 1.8.

Another natural question in this direction is:

Question 4. Are the hypotheses of Theorem 1.8 sufficient to guarantee that (M, g_{hyp}) is arithmetic, and so has infinitely many distinct finite area geodesic surfaces? If a closed hyperbolic 3-manifold contains a closed well-distributed totally geodesic surface, then must it be arithmetic?

Finally, we can use Theorem 1.8 to prove a local rigidity result without any assumptions on the topology of the surfaces in question.

Corollary 1.9. Let (M, g_{hyp}) be a closed hyperbolic 3-manifold. Then there is $\delta > 0$ and A > 0 so that the following holds:

Assume g is a metric on M with sectional curvature bounded above by -1 so that

- \bullet The C^2 distance between g and g_{hyp} measured in g_{hyp} is less than δ
- Σ is a totally geodesic hyperbolic surface in (M, g)
- The area of Σ is greater than A.

Then, g is isometric to g_{hyp} and Σ is homotopic to a totally geodesic surface in (M, g_{hyp}) .

Proof. Given the $\epsilon > 0$ obtained by applying Theorem 1.8 to (M, g_{hyp}) , we can ensure that any metric g and surface Σ as in the statement of Corollary 1.9 is $(1 + \epsilon)$ -quasifuchsian provided that δ was chosen sufficiently small. Next, if A was chosen large enough, we can assume that Σ was not homotopic to one of the finitely many totally geodesic surfaces to which Theorem 1.8 does not apply. Theorem 1.8 then applies to give the conclusion of the corollary.

1.5. **Rigidity of totally umbilic surfaces in negative curvature.** We say a surface is *totally umbilic* if all of its principal curvatures have the same positive constant value at every point. They are to constant mean curvature surfaces as minimal surfaces are to totally geodesic surfaces. A final variation on Question 3 we consider is:

Question 5. Let (M, g) be a Riemannian 3-manifold with sectional curvature bounded above by -c < 0 containing infinitely many distinct totally umbilic surfaces with mean curvature smaller than c. Must (M, g) be hyperbolic?

If the mean curvature of the totally umbilic surfaces is allowed to be large, then one does not expect a rigidity statement due to the fact that metric spheres in hyperbolic space are totally umbilic. It suffices to take a hyperbolic metric and perturb it in a small neighborhood to obtain a variably negatively curved manifold with infinitely many totally umbilic hypersurfaces. The condition that the mean curvature be smaller than c is a natural choice because for every $\epsilon > 0$ there are closed negatively curved 3-manifolds with sectional curvature non-constant and at most -c, and that contain infinitely many totally umbilic surfaces with mean curvature at most $c + \epsilon$. These can be constructed from closed hyperbolic 3-manifolds with arbitrarily large injectivity radius, by perturbing the metric slightly outside of a large injectivity ball and then rescaling the metric depending on the value of c.

We are able to prove the following theorem, which is analogous to Theorem 1.7, and which we view as evidence for a positive answer to Question 5.

Theorem 1.10. Suppose that (M, g) is a closed negatively curved 3-manifold, and that it contains infinitely many distinct totally umbilic surfaces Σ_n as in Question 5. Suppose there is a homotopy equivalence $h: M \to M$ so that the $S_n := h(\Sigma_n)$ are homotopic to a sequence of asymptotically totally umbilic surfaces for a hyperbolic metric g_{hyp} on M. Then (M, g) must have constant curvature.

Totally umbilic surfaces lack the connection to the geodesic flow that totally geodesic surfaces have, and we thus require a different argument from Theorem 1.7. The proof of Theorem 1.10 instead uses the Labourie-Smith theory of k-surfaces, or surfaces for which the product of the principal curvatures, or extrinsic curvature, is constant. Labourie introduced k-surfaces as a higher dimensional analogue of the geodesic flow and proved a number of deep results in this direction [Lab99], [Lab05] (see [Lab02] for a survey.) Their strong rigidity and uniqueness properties allow us to move information from constant to variable negative curvature and thereby obtain the control on the S_n we need to prove Theorem 1.10.

1.6. **Beyond asymptotically Fuchsian.** Very little is understood of the behavior of sequences of quasifuchsian minimal surfaces that fail to be asymptotically geodesic, although recent work by Rao constructed many such examples [Rao23]. As a first step in this direction, we prove the following theorem in Section 8.

Theorem 1.11. *There are asymptotically dense sequences of closed quasifuchsian minimal or pleated surfaces that are not asymptotically Fuchsian.*

1.7. **Related work and context.** The question of whether what is true for totally geodesic surfaces in hyperbolic 3-manifolds remains true for sequences of asymptotically geodesic minimal surfaces has been a focus of recent activity [AA], [CMN22], [KMS23], [Lab22].

More generally, Thurston noticed that closed surfaces with principal curvatures smaller than one are incompressible (see [Lei06] for a proof), and since then surfaces with small principal curvatures have been important in hyperbolic 3-manifold theory. Recent papers in which they play an important role include [BR24], [Bro23], [HL21], [MN24], [NSS25].

Work by Solan studied subgroups of hyperbolic 3-manifold groups that are asymptotic to Fuchsian subgroups in a different sense—that their critical exponents tended to one from below—and proved rigidity and gap theorems in that context [Sol24].

The second author proved density theorems for minimal surfaces in certain negatively curved 3-manifolds [Low21]. The techniques of that paper could be combined with Corollary 1.3 of this paper to prove asymptotic density statements for sequences of minimal surfaces in certain negatively curved 3-manifolds, provided that the minimal surfaces in the sequence were homotopic to asymptotically Fuchsian surfaces in the hyperbolic metric.

Arguments similar to Section 7 have prior to this been used to prove various asymptotic rigidity statements for k-surfaces [ALS22], [ALS24] (see [Alv25] for a survey.)

Finally we mention again the work by X.H. Han that obtains results similar to Theorem 1.1 and its corollaries, and gives applications inspired by analogies to filling curves on surfaces [Han25].

1.8. **Outline.** In Section 2 we give the proof of Theorem 1.1. In Section 3 we prove Theorem 1.6. In Section 4 we establish some structural facts regarding accumulation sets of

asymptotically geodesic surfaces in hyperbolic manifolds. In Section 5 we prove Theorem 1.5. In Section 6 we prove Theorems 1.7 and 1.8. In Section 7 we prove Theorem 1.10. In Section 8 we prove Theorem 1.11.

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2. Proof of Theorem 1.1

Let *M* be a finite volume hyperbolic 3-manifold. Denote by Gr *M* the Grassmann bundle of tangent 2-planes to *M*. We start by recording a useful lemma.

Lemma 2.1. Let $E \subset Gr M$ be a finite collection of finite area totally geodesic surfaces. Then there is $\delta = \delta(E) > 0$ so that if $S \subset M$ is an essential closed immersed surface that is not homotopic to any totally geodesic surface and no essential loop of which is homotopic into a cusp, then $d(\Pi, E) > \delta$ for some tangent plane Π to S in the δ -thick part of M.

We first prove the following.

Claim 2.2. Let $G \subset Gr$ M be a finite collection of closed (compact) totally geodesic surfaces. There is $\delta = \delta(G) > 0$ so that if $S \subset M$ is a closed essential immersed surface whose tangent planes are contained in the δ -neighborhood of G, then S is homotopic to a cover of a surface in G.

Proof. Note that as subsets of Gr M, closed totally geodesic surfaces of M are always embedded in Gr M. In particular, distinct surfaces in E are disjoint as subsets of Gr M.

We may first take $\delta > 0$ small enough so the δ -neighborhoods of the components of G are all disjoint from each other in GrM. Since S is connected, we may assume it lies in the δ -neighborhood of a component T of G.

Thus, for each point $p \in S$, there is a unique nearest point $\pi(p) \in T$. We can construct a homotopy having each point $p \in S$ traverse the geodesic segment in M from p to $\pi(p)$. Provided δ was chosen small enough, the map π is a local diffeomorphism, and so a covering map. We conclude S is homotopic to a cover of T.

We now give the proof of Lemma 2.1.

Proof. We choose δ smaller than the Margulis constant and the δ given by previous claim applied to the closed surfaces in E. We also require that the closed surfaces in E are contained in the δ -thick part of M. By the previous claim and our choice of δ , S must have a tangent plane at a distance of at least δ from every tangent plane to every closed totally geodesic surface in E. It is therefore enough to show that S has some tangent plane at a distance of at least δ from every tangent plane to a noncompact surface in E. Assume for contradiction that this is not the case.

After perturbing S slightly we can ensure that it intersects the boundary of the δ -thin part $M^{\leq \delta}$ transversely. Then every connected component of the intersection of S with $M^{\leq \delta}$ must be homeomorphic to a disk or an annulus, since S is essential. Choosing δ smaller if necessary, reasoning as in Claim 2.2 we can show that every connected component of the intersection $S \cap M^{\geq \delta}$ must be contained in a small neighborhood of at most one finite area totally geodesic surface in E. The only way that $S \cap M^{\geq \delta}$ could be contained in a union of at least two distinct finite area totally geodesic surfaces (while not being contained in just one) would be if one of the annuli components of the intersection of S with the thin part included to a parabolic element of $\pi_1(M)$ – such an annulus would have one boundary circle on a connected component of a component of $S \cap M^{\geq \delta}$ near one finite area totally geodesic surface and one boundary circle on a component of $S \cap M^{\geq \delta}$ near another finite area totally geodesic surface—which is contrary to our assumption that S contained no essential loops that could be homotoped into a cusp.

Therefore every connected component of the intersection of S with the thin part is contained in a small neighborhood of the same finite area surface Σ_0 , and the core curves of all annuli in the intersection of *S* with the thin part are contractible in *S*. In the same way as in the proof of Claim 2.2 we can then homotope *S* to a new surface *S'* so that $S' \cap M^{\geq \delta}$ is contained in Σ_0 . Therefore for some choice of basepoint on Σ_0 the fundamental group of S' injectively includes to a subgroup of the fundamental group of Σ_0 , which is impossible because Σ_0 is cusped.

Therefore S has tangent planes at a distance of at least δ to all tangent planes to noncompact surfaces in *E*, which completes the proof.

Below, for $p \in Gr M$, denote by $\Delta_R(p)$ denote the geodesic disc of radius R tangent to p. For a metric space X, we let $N_{\delta}A$ denote the δ -neighborhood of subset $A \subset X$. We say $A \subset X$ is ϵ -dense if $N_{\epsilon}A = X$ – in other words, A intersects every ball of radius ϵ in X.

2.1. When M has finitely many finite area totally geodesic surfaces. We first handle the case that M has only finitely many finite-area totally geodesic surfaces. Throughout this bit, let *E* denote the union of all the finite-area totally geodesic surfaces of *M*.

Lemma 2.3. Assume that M is compact. Then for every $\epsilon > 0$ and every $\delta > 0$, there exists $R_0(\epsilon, \delta)$ so if $R > R_0$ and $d(p, E) \ge \delta$, then $\Delta_R(p)$ is ϵ -dense in Gr M.

Proof. If the statement is false, then there is $\epsilon, \delta > 0$ and a sequence of R_i tending to infinity so that for every positive integer j, there is $p_i \notin N_\delta(E)$ so that $\Delta_{R_i}(p_i)$ is not ϵ -dense in Gr M. In particular, $\Delta_{R_i}(p_i)$ misses an ϵ -ball $B_{\epsilon}(q_i)$ around some $q_i \in Gr M$.

From the compactness of $\operatorname{Gr} M - N_{\delta}(E)$ and $\operatorname{Gr} M$, we can extract common convergent subsequences of (p_i) and (q_i) converging to some $p \notin N_{\delta}(E)$ and $q \in Gr M$, respectively. For simplicity, we also denote these subsequences by (p_i) and (q_i) .

By construction, $\Delta_{R_j}(p_j)$ does not intersect $B_{\epsilon}(q_j)$. For sufficiently large j, we can also ensure that $\Delta_{R_i}(p_j)$ does not intersect $B_{\epsilon/2}(q)$.

In particular, if we fix a (sufficiently large) k, then for $j \ge k$, $\Delta_{R_k}(p_j)$ does not intersect $B_{\epsilon/2}(q)$. But as k is fixed, the Hausdorff distance between $\Delta_{R_k}(p_j)$ and $\Delta_{R_k}(p)$ goes to zero as $j \to \infty$. Thus for j large enough, we have that $\Delta_{R_k}(p) \subset N_{\epsilon/4}\Delta_{R_k}(p_j)$. We conclude $\Delta_{R_k}(p)$ does not intersect $B_{\epsilon/4}(q)$ and so the geodesic plane $\Delta(p) := \bigcup_{k \ge 1} \Delta_{R_k}(p)$ through p is not dense in Gr M.

This contradicts the theorem of Ratner and Shah ([Rat91],[Sha91]) which tells us that the geodesic plane through any point $p \in Gr M - E$ is dense in Gr M.

If *M* has cusps, essentially the same argument shows the following.

Lemma 2.4. For every $\epsilon > 0$, $\delta > 0$ and $\eta > 0$, there exists $R_0(\epsilon, \delta, \eta)$ so that if $R > R_0$, $p \in M^{\geq \eta}$ and $d(p, E) \geq \delta$, then $\Delta_R(p)$ is ϵ -dense in $Gr M^{\geq \eta}$, where $M^{\geq \eta}$ is the η -thick part of M.

We can now prove Theorem 1.1 when *M* has only finitely many finite area totally geodesic surfaces.

Proof of Theorem 1.1, special case. First assume that M is compact. Let $\epsilon > 0$ be the radius of B and let $\delta > 0$. By Lemma 2.3, there is $R_0 > 0$ so whenever $d(p, E) > \delta$, then $\Delta_R(p)$ is ϵ -dense in Gr M.

Let S be a $(1 + \xi)$ -quasifuchsian minimal surface distinct from the surfaces in E. A result of Seppi tells us the absolute values of the principal curvatures of S are uniformly bounded by $C \log(1 + \xi)$, where C is a universal constant [Sep16]. In particular, if we denote by $D_R^S(p)$ the intrinsic disc in S of radius R passing through p, for ξ sufficiently small depending on ϵ , we have that

$$\Delta_R(p) \subset N_\epsilon(D_R^S(p)).$$

From Lemma 2.1, we know that every quasifuchsian surface $S \subset GrM$ has at least one point $p(S) \in GrM$ outside of $N_{\delta}E$. In particular, $D_{R}^{S}(p(S))$ is 2ϵ -dense in GrM.

If M has cusps then one can apply Lemma 2.1 and Lemma 2.4 to argue in the same way, replacing M with the η -thick part of M in the relevant places.

2.2. When M has infinitely many finite area totally geodesic surfaces.

Lemma 2.5. Assume that M is compact. Then for every $\epsilon > 0$, there exists a collection $E \subset Gr M$ of finitely many closed totally geodesic surfaces such that for every $\delta > 0$, there is $R_0 > 0$ so if $R > R_0$ and $d(p, E) \ge \delta$ then $\Delta_R(p)$ is ϵ -dense in Gr M.

Proof. Let $\epsilon > 0$. We choose E to be the union of all the totally geodesic surfaces of M which are not $\epsilon/4$ -dense in Gr M. From the equidistribution theorem of Mozes and Shah ([MS95]), we know E is the union of finitely many surfaces.

Now fix $\delta > 0$. We now wish to show there is $R_0 = R_0(\epsilon, \delta, E)$ so whenever $p \notin N_\delta(E)$, then $\Delta_R(p)$ is ϵ -dense in Gr M. If we suppose that is not true, then we may find, as in the proof of Lemma 2.3, a point $p \in \operatorname{Gr} M - N_\delta(E)$ so the geodesic plane $\Delta(p)$ through p misses a ball of radius $\epsilon/4$ around some point q. If p does not lie in a totally geodesic surface, then this contradicts the Ratner-Shah theorem on geodesic planes, as explained before. If p does lie in a totally geodesic surface, then it has to be a surface not in E, which by construction is $\epsilon/4$ -dense in Gr M, again a contradiction.

Proof of Theorem 1.1 in general. Let $\epsilon > 0$, and assume that M is compact. By Lemma 2.5, there is a finite collection $E \subset \operatorname{Gr} M$ of geodesic surfaces, $\delta > 0$ small enough so $\operatorname{Gr} M - N_{\delta}(E)$ is nonempty, and $R_0 > 0$ so that for every $R > R_0$, if $p \in \operatorname{Gr} M - N_{\delta}(E)$ then $\Delta_R(p)$ is ϵ -dense in $\operatorname{Gr} M$.

Now, by the same arguments (the last three paragraphs) from the proof of Theorem 1.1 in the previous case, we can show that for ξ sufficiently small, $(1 + \xi)$ -quasifuchsian surfaces distinct from those contained in E are 2ϵ -dense in E of E.

The arguments in the case that M has cusps are again similar.

3. Nonexistence of asymptotically geodesic surfaces in infinite volume

In this section we show that, unlike in the finite-volume case, there is a gap between totally geodesic surfaces and non-totally geodesic essential surfaces for geometrically finite hyperbolic 3-manifolds of infinite volume.

Theorem 3.1. Let $M = \Gamma \backslash \mathbf{H}^3$ be an infinite volume geometrically finite hyperbolic 3-manifold. Then there is $\epsilon = \epsilon(\Gamma) > 0$ so all $(1 + \epsilon)$ -quasifuchsian closed surface subgroups of Γ are Fuchsian.

The same proof also gives the following theorem.

Theorem 3.2. Let $M = \Gamma \backslash \mathbf{H}^3$ be an infinite volume geometrically finite hyperbolic 3-manifold. Then there is $\epsilon = \epsilon(M) > 0$ so that if $S \subset M$ is a closed minimal surface with principal curvatures uniformly bounded by ϵ , then S is totally geodesic.

Remark 3.3. We expect that similar statements could be obtained in higher dimensions for maximal surfaces (i.e., surfaces that cannot be homotoped into a proper totally geodesic submanifold) using [LO24][Theorem 1.7], which proved among other things that convex cocompact hyperbolic n-manifolds of infinite volume contain only finitely many closed maximal totally geodesic submanifolds of dimension at least two. It is probable that the same statement is true in the geometrically finite case. The question of whether there are convex cocompact hyperbolic n-manifolds without Fuchsian ends for n > 3 is still unresolved, although Kerckhoff-Storm gave a negative answer locally [KS12].

Proof. I. A proof when core M is compact and has totally geodesic boundary.

We first give a proof in the special case that core M is compact and has totally geodesic boundary. Let \hat{M} be the closed hyperbolic 3-manifold obtained by doubling core M

Suppose $(Q_i) \leq \Gamma$ is a sequence of asymptotically Fuchsian surface subgroups. They give rise to a sequence of immersed minimal surfaces $f_i: S_i \to M$ with $(f_i)_*(\pi_1 S_i) = Q_i$ [Uhl83], and by the maximum principle $f_i(S_i)$ always lies in the convex core of M. (The S_i are obtained by minimizing area in the covering spaces corresponding to the injective inclusions of their fundamental groups.) In addition, $f_i: S_i \to \hat{M}$ is a sequence of asymptotically geodesic minimal surfaces by [Sep16]. These surfaces are not dense in \hat{M} , as they never touch $\hat{M} - M$. This contradicts Theorem 1.3.

II. The proof in general.

The crucial ingredient in the proof is Theorem 1.5 of [BO22] that states that for a geometrically finite infinite volume hyperbolic 3-manifold M there are only finitely many finite area totally geodesic surfaces contained in core M, and these are the only closed immersed (not necessarily compact) totally geodesic planes in core M. We denote their union, as a subset of $Gr_2 M$, by E.

Suppose $(Q_i) \leq \Gamma$ is a sequence of asymptotically Fuchsian surface subgroups. As before they give rise to a sequence of minimal surfaces $S_i \subset \operatorname{core} M$ with $\pi_1 S_i = Q_i$ such that the L^{∞} norms of the principal curvatures of S_i tend to zero as $i \to \infty$.

If the S_i were not totally geodesic, then the same arguments as the proof of Claim 2.2 and Lemma 2.1 show that there is $\delta > 0$ and $p_i \in S_i$ so that the tangent plane $\Delta(p_i)$ to S_i at p_i is at a distance of at least δ from E in Gr_2M and contained in the δ -thick part of core M.

The proof of the following statement can be proved by an argument by contradiction similar to the proof of Lemmas 2.3 and 2.4, using the fact from Benoist-Oh ([BO22][Theorem 1.5]) that every immersed totally geodesic plane not contained in *E* leaves the convex core of *M*.

Claim 3.4. There is $R = R(\delta) > 0$ so that for every p in the intersection of the δ -thick part of M with $Gr_2(\operatorname{core} M) - N_{\delta}E$, the totally geodesic disc $\Delta_R(p)$ of radius R based at p leaves $\operatorname{core} M$.

The fact that the principal curvatures of S_i are going to zero in L^{∞} norm tells us that the Hausdorff distance between the intrinsic discs $D_R(p_i) \subset S_i$ of radius R centered at p_i and the geodesic discs $\Delta_R(p_i)$ goes to zero as $i \to \infty$. In particular, $\Delta_R(p_i)$ leaves core M for large enough i, contradicting that the surfaces S_i all lie in core M.

4. Possible accumulation sets in higher dimensions

Let *M* denote a closed *d*-dimensional hyperbolic manifold.

Let (X_n) be a sequence of sets in the Grassman bundle $\operatorname{Gr} M = \operatorname{Gr}_2 M$ of tangent 2-planes to M. The accumulation set of (X_n) , denoted $\operatorname{acc}(X_n)$, consists of the points $x \in \operatorname{Gr} M$ arising as limits of sequences $x_n \in S_n$. Note that this is a strictly stronger condition than if we required only that the points in the set arose as subsequential limits of sequences x_n . Note also that (X_n) is asymptotically dense exactly when its accumulation set is all of $\operatorname{Gr} M$ and (X_n) is always asymptotically dense in its accumulation set. Finally, we point out that the accumulation set of a sequence that converges in the Hausdorff topology is the Hausdorff limit of that sequence.

The goal of this section is to prove the following theorem.

Theorem 4.1. Let S_n be a sequence of asymptotically Fuchsian minimal surfaces in M. Then, the accumulation set of S_n is a finite union E of totally geodesic submanifolds of M of dimension $3 \le k \le d$.

Remark 4.2. The same proof shows that the statement of the theorem holds for a sequence S_n of asymptotically geodesic surfaces, that are not assumed to be minimal.

Lemma 4.3. Suppose S_n is a sequence of asymptotically Fuchsian minimal surfaces that is not contained in a finite union of closed totally geodesic submanifolds of M. Then S_n is asymptotically dense.

Proof. The proof of the Lemma makes use of the Ratner-Shah theorem and closely follows the proof of Theorem 1.3 in three dimensions.

Following similar arguments to the proofs of Lemmas 2.3, 2.5, we can show:

Lemma 4.4. For every $\epsilon > 0$ and $\delta > 0$, there is a finite union of totally geodesic submanifolds $E \subset M$ with dimensions in $\{2, \ldots, d-1\}$ and $R_0(\epsilon, \delta, E) > 0$ so that if $R > R_0$ and p is a tangent 2-plane to M at a distance of at least δ from every tangent 2-plane to E, then $\Delta_R(p)$ is ϵ -dense in $Gr_2 M$.

We can also prove the following lemma analogous to Lemma 2.1.

Lemma 4.5. Suppose $E \subset M$ is a finite union of proper totally geodesic submanifolds of M and let S be an essential surface of M that is not homotopic to a surface contained in E. Then, there is $\epsilon = \epsilon(E) > 0$ so that there is a tangent 2-plane p to S at a distance of at least ϵ from every tangent 2-plane to E.

Proof. It suffices to show that for $\epsilon > 0$ small enough, if $d_{Gr_2(M)}(S, E) \le \epsilon$, then S can be homotoped to a surface contained in E. To do so, as in the proof of Claim 2.2, we let $\pi : S \to E$ be the nearest point projection, which is well-defined if $\epsilon > 0$ was chosen small enough. We homotope S into E by having each point E traverse the geodesic joining E to E to E.

We may now finish the proof of Lemma 4.3. Let $\epsilon > 0$ and $\delta > 0$. By Lemma 4.4, we may choose a finite union of totally geodesic submanifolds $E \subset M$ and and R > 0 so that whenever $d_{\operatorname{Gr}_2 M}(p, E) > \delta$, then the geodesic disc $\Delta_R(p)$ is ϵ -dense in Gr M.

From Lemma 4.5, we know that there is a sequence of tangent planes $p_n \subset S_n$ with $d_{Gr_2M}(p_n, E) \ge \delta$. Here we are using the fact that an essential minimal surface can be homotoped into a totally geodesic submanifold if and only if it is already contained in it.

From the work of Jiang (section 2 of [Jia21]) we know that for n large enough the S_n are smooth surfaces without branch points, and that their principal curvatures converge uniformly to zero as $n \to \infty$. In particular, if we denote by $D_R^n(q)$ the intrinsic disc in S_n of radius R passing through q, we have that for n large enough, $d_{Gr_2M}(D_R^n(p_n), \Delta_R(p_n)) \le \epsilon$.

Thus, there is N so that for $n \ge N$, the intrinsic discs $D_R^n(p_n)$ are ϵ -dense in Gr M. In particular, S_n are 2ϵ -dense for $n \ge N$.

Lemma 4.3 above shows that if (S_n) are asymptotically Fuchsian minimal surfaces that are *not* asymptotically dense, then their accumulation set is contained in a finite union E of totally geodesic submanifolds.

Denote by \mathcal{A} the accumulation set of the S_n . Let \mathcal{G} be the set of all finite unions of totally geodesic submanifolds that contain \mathcal{A} . We claim that the intersection F of the sets in \mathcal{G} is also an element of \mathcal{G} . To see this, enumerate the elements of \mathcal{G} as $g_1, g_2, ...$ We can write the intersection $F = \bigcap_{i=1}^{n} g_i$:

$$F = \bigcap_{i=1}^{\infty} F_i.$$

We know that $F_{i+1} \subset F_i$, and that either $F_i = F_{i+1}$, or else the sum of the dimensions of the connected totally geodesic submanifolds of F_{i+1} is smaller than those of F_i . Therefore the sequence of F_i is eventually constant, and equal to F.

4.1. **Claim:** $F = \mathcal{A}$. Assume for contradiction that \mathcal{A} is a proper subset of F, and let Σ be a closed totally geodesic submanifold of F that contains a point that is not contained in \mathcal{A} . We know that $\mathcal{A} \cap \Sigma$ is not contained in a union of closed totally geodesic submanifolds of Σ , otherwise we could take F to be a smaller set.

If there were some tangent plane Π to Σ in \mathcal{A} that was not contained in any closed totally geodesic submanifold of Σ , then the totally geodesic plane tangent to Π would be dense in Σ by Ratner's theorems. Since Π is in the accumulation set of the S_n and the S_n are asymptotically geodesic, this implies that all of Σ is in the accumulation set of the S_n , which finishes the argument in this case.

Assume on the other hand that each tangent plane Π in \mathcal{A} to Σ is contained in a closed totally geodesic Σ_{Π} that is a proper submanifold of Σ , so that no closed totally geodesic submanifold of Σ_{Π} contained the totally geodesic plane tangent to Π . Then since the totally geodesic plane tangent to Π is dense in Σ_{Π} by Ratner's theorems, in the same way as in the

previous paragraph all of Σ_{Π} must be contained in \mathcal{A} . This shows that $\mathcal{A} \cap \Sigma$ is a union of closed totally geodesic submanifolds.

Recall that a closed totally geodesic submanifold in $\mathcal{A} \cap \Sigma$ is *maximal* if it is not contained in a closed totally geodesic submanifold of $\mathcal{A} \cap \Sigma$ of higher dimension. Then every closed totally geodesic submanifold of $\mathcal{A} \cap \Sigma$ is contained in a maximal totally geodesic submanifold of $\mathcal{A} \cap \Sigma$. We claim that there are only finitely many maximal totally geodesic submanifolds of $\mathcal{A} \cap \Sigma$. If not, then we can choose a sequence $\Sigma'_1, \Sigma'_2,...$ of them. By Ratner's theorems, the Σ'_i must be dense in a closed totally geodesic submanifold Σ' of Σ . Reasoning similar to before shows that Σ' is contained in $\mathcal{A} \cap \Sigma$, which contradicts maximality of the Σ'_i .

Therefore there are only finitely many maximal totally geodesic submanifolds of $\mathcal{A} \cap \Sigma$. Since $\mathcal{A} \cap \Sigma$ is a union of closed totally geodesic submanifolds and each closed totally geodesic submanifold of $\mathcal{A} \cap \Sigma$ is contained in a maximal such, $\mathcal{A} \cap \Sigma$ is equal to the union of the maximal totally geodesic submanifolds it contains, of which there are only finitely many. Since $\mathcal{A} \cap \Sigma$ is not contained in finite union of closed totally geodesic submanifolds of Σ , the only possibility for $\mathcal{A} \cap \Sigma$ is that it is equal to Σ , which finishes the proof.

5. Realizing accumulation sets in higher dimensions

In this section, we will prove Theorem 1.5, restated below for convenience.

Theorem 5.1. Suppose M is a closed hyperbolic d-manifold containing two closed totally geodesic 3-dimensional submanifolds N_1 and N_2 that intersect along a closed totally geodesic surface.

Then, there exists a sequence (S_n) of closed connected asymptotically Fuchsian pleated surfaces whose accumulation set is $N_1 \cup N_2$. There also exists a sequence (S_n) of closed connected asymptotically geodesic minimal surfaces whose limit in the Hausdorff topology of M is $N_1 \cup N_2$.

This is in contrast with the case where all the S_n are totally geodesic. In that setting, using the work by Mozes-Shah [MS95] we can prove the following proposition.

Proposition 5.2. Let M be a closed hyperbolic d-manifold. The accumulation set of a sequence $S_n \subset M$ of closed totally geodesic surfaces consists of a closed connected totally geodesic submanifold S (i.e., a totally geodesic submanifold S whose lift to the Grassmann bundle of tangent dim(S) planes to M is connected.)

Proof of Proposition 5.2. Let $G = SO_0(d, 1)$ and $H = SO_0(2, 1) \le G$.

For each n, let \hat{S}_n be a closed H-orbit in Fr $M = \Gamma \backslash G$ whose projection to $\operatorname{Gr}_2 M$ is equal to S_n . Let μ_n be the homogeneous probability measure supported on \hat{S}_n .

Claim. Let π : Fr $M \to \operatorname{Gr}_2 M$ denote the projection sending a frame (p, v_1, \dots, v_d) to $(p, \operatorname{span}\{v_1, v_2\})$. Then,

$$\operatorname{acc}(\{S_n\}) = \pi \left(\bigcap_{\mu} \operatorname{supp}(\mu)\right),$$

where μ ranges over all weak-* limits of subsequences of (μ_n) .

The theorem of Mozes-Shah implies that each μ is the homogeneous measure supported on a closed orbit of some closed Lie subgroup $L_{\mu} \leq G$ properly containing H. In particular, the projection of $\cap_{\mu} \operatorname{supp}(\mu)$ to $\operatorname{Gr}_2 M$ is connected as the 2-plane Grassmann bundle to a totally geodesic submanifold $N \subset M$ that corresponds to the connected subgroup of G obtained as the intersection of the L_{μ} , which proves the proposition assuming the claim.

We now prove the claim.

Let $\mu_{n_k} \stackrel{\star}{\rightharpoonup} \mu$ denote a convergent subsequence of (μ_n) . As μ_{n_k} is the homogeneous measure supported on \hat{S}_{n_k} , if $x_{n_k} \in \hat{S}_{n_k}$ is a convergent sequence, then $\lim_{k \to \infty} x_{n_k} \in \text{supp } \mu$. We are using here the fact from [MS95] that the closed subgroups $L_{\mu_{n_k}}$ corresponding to the μ_{n_k} are contained in the closed subgroup L_{μ} corresponding to μ for large enough k. Conversely, any point in supp μ can be realized as a limit of $x_{n_k} \in \hat{S}_{n_k}$, or else there would be a neighborhood of that point to which μ assigned zero measure which is impossible. Therefore, $\operatorname{acc}(\hat{S}_{n_k}) = \operatorname{supp} \mu$.

We conclude by noting that $\operatorname{acc}(\hat{S}_n)$ is the intersection of $\operatorname{acc}(\hat{S}_{n_k})$ over all subsequences (\hat{S}_{n_k}) such that μ_{n_k} is convergent. That the former is contained in the latter is clear. To see the other containment, assume for contradiction that there is a point p in the intersection of $\operatorname{acc}(\hat{S}_{n_k})$ over all subsequences (\hat{S}_{n_k}) such that μ_{n_k} is convergent, but that p is not contained in $\operatorname{acc}(\hat{S}_n)$. If this is the case, then there is some $\epsilon > 0$ so that for any N, there is some k > N so that every point on \hat{S}_k is at a distance of at least ϵ from p. Passing to a convergent subsequence of the probability measures corresponding to the \hat{S}_k , we obtain a weak-* limit measure that does not contain p, which is a contradiction.

5.1. **Manifolds satisfying the hypotheses of Theorem 5.1.** The lattices in hyperbolic space we consider will be arithmetic of simplest type. We give now a description of their basic properties and facts about them that will be relevant to our construction. We follow closely the reference [Mil76][Section 2], see that paper for further details and references.

We give the construction only in the four-dimensional case, as the higher dimensional case is very similar. but Let $q = x_1^2 + \cdots + x_4^2 - \sqrt{p}x_5^2$, for p prime. Then, SO(q, $\mathbf{Z}[\sqrt{p}]$) is a lattice in SO(q, \mathbf{R}). A quadratic form is *anisotropic* if it does not represent zero rationally. Since q is anisotropic, the lattice SO(q, $\mathbf{Z}[\sqrt{p}]$) is cocompact. There is a real invertible matrix T so that $T^tqT = q_0$, for q_0 the standard signature (4, 1) quadratic form. Therefore

 $T^{-1}\operatorname{SO}(q,\mathbf{R})T = \operatorname{SO}(4,1),$

$$\Gamma := T^{-1} \operatorname{SO}(q, \mathbf{Z}[\sqrt{p}]) T \cap \operatorname{SO}_0(4, 1)$$

is a lattice in $SO_0(4,1) = Isom^+ \mathbf{H}^4$, and $M := \Gamma \backslash \mathbf{H}^4$ is a closed hyperbolic 4-manifold. Let $q_1 = x_1^2 + x_2^2 + x_3^2 - \sqrt{p}x_5^2$ and $q_2 = x_2^2 + x_3^2 + x_4^2 - \sqrt{p}x_5^2$. Define

$$\Gamma_i := T^{-1} \operatorname{SO}(q_i, \mathbf{Z}[\sqrt{p}]) T \cap \operatorname{SO}_0(d, 1).$$

The groups Γ_i can be seen as subgroups of Isom⁺ H_i , where H_i is the hyperbolic 3-plane $\mathbf{H}^4 \cap \{x_1 = 0\}$ for i = 1 and $\mathbf{H}^4 \cap \{x_2 = 0\}$ for i = 2. In particular, $N_i := \Gamma_i \setminus H_i$ are totally geodesic 3-suborbifolds of M. They meet orthogonally along the totally geodesic 2-orbifold $T = \Gamma \setminus (\mathbf{H}^4 \cap \{x_1, x_2 = 0\})$.

The lattice Γ may have torsion (i.e., M may be an orbifold), but it is possible to pass to finite index subgroups that do not. For a prime ideal q in the ring of integers of $\mathbf{Q}[\sqrt{p}]$, the congruence subgroup $\Gamma(q)$ of Γ is defined as follows. Note that all entries of each element of Γ are algebraic integers in $\mathbf{Q}[\sqrt{p}]$. We say that $\gamma \in \Gamma$ satisfies $\gamma \equiv 1 \mod q$ if each of its diagonal entries is congruent to $1 \mod q$, and each other entry off the diagonal is congruent to $0 \mod q$. The matrices in $\Gamma(q)$ form a normal subgroup of Γ . For all but finitely many q, $\Gamma(q)$ will be torsion free. The lifts of N_1 and N_2 to $\Gamma(q) \backslash \mathbf{H}^4$ intersect in a totally geodesic surface each connected component of which finitely covers $N_1 \cap N_2$. This gives examples of manifolds satisfying the hypotheses of Theorem 5.1.

5.2. **Proof of Theorem 5.1.** For the most part we follow the notation and terminology from [AA]. The (ϵ, R) -good curves in M are the closed geodesics with complex translation length 2ϵ -close to 2R. The (ϵ, R) -good pants, are the maps $f: P \to M$ from a pair of pants P taking the cuffs of P to (ϵ, R) -good curves and so that f restricted to the interior of P is an immersed surface with principal curvatures bounded above by a constant $c(\epsilon)$ tending to zero as ϵ tends to zero. Below, $O(\epsilon)$ will be used to denote any quantity that tends to 0 as $\epsilon \to 0$.

From the work of Kahn-Wright [KW21], given $\epsilon > 0$, there is $R_0(\epsilon) > 0$ so for every $R > R_0(\epsilon)$, both submanifolds N_i contains a $(1 + O(\epsilon))$ -quasifuchsian surface $S_i(\epsilon, R)$ that is made out of one copy of each (ϵ, R) -good pants in the set of all (ϵ, R) -good pants in N_i , which we denote by $\Pi_{\epsilon,R}(N_i)$.

Using the work of Liu-Marković [LM15], one can show there are numbers $n_i(\epsilon, R)$ for i=1,2 so that there are *connected* $(1+O(\epsilon))$ -quasifuchsian surfaces, denoted also $S_i(\epsilon, R)$ made out of $n_i(\epsilon, R)$ copies of each good pants (see [AA][Section 4]). We also know that given sequences $\epsilon_j \to 0$ and $R_j \to \infty$ (with $R_j \ge R_0(\epsilon_j)$), the surfaces $S_i(\epsilon_j, R_j)$ equidistribute in $Gr_2(N_i)$ (see [AA][Theorem 6.1] which proves the corresponding statement for surfaces made from pleated pants— the same argument applies to the surfaces $S_i(\epsilon_j, R_j)$ built from asymptotically totally geodesic pants that we consider).

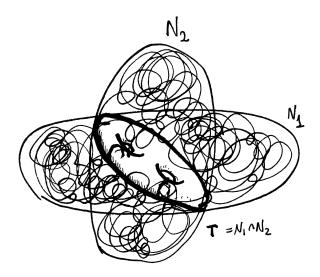


Figure 1. The scrawly curve represents the surfaces $S(\epsilon_j, R_j)$, which become dense in $N_1 \cup N_2$ as $j \to \infty$.

Let T be the totally geodesic surface along which N_1 and N_2 intersect. From the proof of the Ehrenpreis conjecture by Kahn-Marković [KM15], we know that T has a finite cover \hat{T} admitting a pants decomposition Π_T of (ϵ, R) -good pants.

Choose a cuff γ_1 of T that is part of Π_T and let $\pi^- \in \Pi^-_{\epsilon,R}(\gamma_1)$ and $\pi^+ \in \Pi^+_{\epsilon,R}(\gamma_1)$ be immersed pants in T that are (ϵ, R) -well glued along γ_2 .

Using the fact that the pants in $\Pi_{\epsilon,R}(N_1)$ are well-distributed along γ_1 (see Theorem 3.3 in [KW21]), we may find pants $p^- \in \Pi^-_{\epsilon,R}(N_1)$ and $p^+ \in \Pi^+_{\epsilon,R}(N_1)$ in $S_1(\epsilon,R)$ that are (ϵ,R) -well glued along γ_1 and so that $\operatorname{ft} p^-$ is ϵ/R -close to $\operatorname{ft} \pi^-$.

Thus we may cut S_1 and T along γ_1 and glue p^- to π^+ and π^- to p^+ in a $(2\epsilon, R)$ -good fashion. The reglued surface S' will still be closed, connected and $(1 + O(\epsilon))$ -quasifuchsian, by Theorem 2.2 from [KW21].

We may choose another cuff γ_2 of Π_T and similarly perform regluings to join S_2 to S' in a nearly Fuchsian way, giving us a new surface $S = S(\epsilon, R)$. By their construction from asymptotically totally geodesic pants whose union is becoming dense in the Grassman bundle of tangent 2-planes to $N_1 \cup N_2$, if we take $\epsilon_j \to 0$ and $R_j \to \infty$ (where $R_j \ge R_0(\epsilon_j)$), the Hausdorff limit of the surfaces $S(\epsilon_j, R_j)$ is $Gr_2 N_1 \cup Gr_2 N_2$ in $Gr_2 M$.

At this point, what is missing for us to conclude the statement of the theorem is that we have not shown $S(\epsilon_j, R_j)$ are asymptotically Fuchsian. While $S(\epsilon, R)$ are made out of gluing (ϵ, R) -good pants via (ϵ, R) -good gluings, we cannot use Theorem 2.2 from [KW21] as the loxodromic elements corresponding to the cuffs of the pants used to build $S(\epsilon, R)$ do not

all lie on the same copy of $SO_0(3,1)$ inside $SO_0(4,1)$. (The pants of N_1 lie in a distinct copy from the pants in N_2 .)

On the other hand, Hamenstädt [Ham14][Proposition 6.2], shows surfaces S in a compact locally symmetric space M of rank 1 made out of (ϵ, R) -good pants glued via (ϵ, R) -good gluings are L-quasigeodesic, i.e., their universal cover $\tilde{S} \subset \tilde{M}$ is the image of a (L, 0)-quasiisometric embedding of \mathbf{H}^2 . In the proposition below we show we can make L arbitrarily close to 1 provided $\epsilon > 0$ is sufficiently small and R > 0 sufficiently large. (Hamenstädt commented that this should be the case [Ham14][pg. 2].) This follows from the fact that intrinsic geodesics on the surfaces S made out of (ϵ, R) -good pants glued via (ϵ, R) -good gluings are curves in \mathbb{H}^d to which the following proposition applies.

Proposition 5.3. For every $\epsilon > 0$ and c > 0, there is $\delta > 0$ so that a piecewise differentiable curve $\gamma : \mathbf{R} \to \mathbf{H}^d$ composed of segments with geodesic curvature at most δ with length at least c > 0 and joined at break angles at most δ is a $(1 + \epsilon)$ -quasigeodesic. Here $\delta = \delta(d, \epsilon)$.

Proof. First, we note that for any $\kappa > 0$, if δ was taken small enough, γ can be homotoped near the break points to a smooth curve $\hat{\gamma}$ with principal curvatures smaller than κ . This would be clear for curves in \mathbf{R}^d , and we can conclude it in our situation by applying this fact to rescalings of the hyperbolic metric that are sufficiently C^2 -close to Euclidean space.

Next, for any r > 0, there exists $\kappa_0(r)$ so if a complete bi-infinite curve $\overline{\gamma}$ in \mathbf{H}^d has curvature $\kappa < \kappa_0(r)$, then the boundary $\partial N_r(\overline{\gamma})$ of the r-neighborhood $N_r(\overline{\gamma})$ of $\overline{\gamma}$ is strictly convex – i.e., the second fundamental form of $\partial N_r(\overline{\gamma})$ is positive definite at every point. To see this, suppose to the contrary that we can find curves $\gamma_n : \mathbf{R} \to \mathbf{H}^d$ with curvatures $\kappa_n \to 0$, so $\partial N_r(\gamma_n)$ is never strictly convex. Let κ_n be points on κ_n so that for each κ_n there is a point at a distance of less than κ_n in the boundary of κ_n where strict convexity fails. Translating the κ_n by elements of κ_n in the boundary of κ_n we can assume that the κ_n all intersect a fixed compact set. Thus up to passing to a subsequence the κ_n smoothly converge to a geodesic κ_n on compact sets. Therefore, the boundaries κ_n smoothly converge to κ_n on compact sets, which implies κ_n has a point where the second fundamental form is not positive. This contradicts the fact that the boundary of the κ_n -neighborhood of a geodesic in κ_n is strictly convex.

Finally, a complete quasigeodesic curve $\overline{\gamma}$ whose r-neighborhood is strictly convex contains a unique complete geodesic in its r-neighborhood.

Combining the three paragraphs above, we can conclude that if δ was chosen small enough, there is a complete geodesic at a C^1 distance as small as desired from γ as in the statement of the proposition. This shows that γ is a $(1+\epsilon)$ -quasigeodesic, provided $\delta = \delta(\epsilon)$ was taken small enough.

It follows from [Jia21][Section 2.3] that the $S(\epsilon_j, R_j)$ are homotopic to minimal surfaces S_j without branch points. Arguing as in [Jia21] [Section 2.3, 3.2] and [CMN22][Lemma 4.3], we can show that the S_j have the same accumulation set as the $S(\epsilon_j, R_j)$.

To explain in more detail, one can argue by contradiction. Suppose that there is some $\epsilon > 0$ and points p_j on S_j the tangent planes to which are at a distance of at least ϵ in the Grassman bundle from any tangent plane to $S(\epsilon_j, R_j)$. Choosing lifts D_j of the S_j to the universal cover that all intersect a fixed compact set containing lifts of \tilde{p} , we know that their limit sets are quasicircles that converge, up to passing to a subsequence, to a round circle that is the boundary at infinity of a totally geodesic disk D. Jiang [Jia21] shows that the D_j smoothly converge to D on compact subsets. But it is also the case that the lifts of the $S(\epsilon_j, R_j)$ Hausdorff converge to D on compact subsets. Projecting D_j and the lift of $S(\epsilon_j, R_j)$ back down to M then gives a contradiction for large enough j.

6. Rigidity of totally geodesic surfaces in negative curvature

6.1. Given Corollary 1.3, the proof of Theorem 1.8 is essentially the same as the proof of [Low23][Theorem 1.5]. We restate Theorem 1.8 for convenience.

Theorem 6.1. Let (M, g_{hyp}) be a closed hyperbolic 3-manifold. Then there is $\epsilon > 0$ and a finite collection of closed totally geodesic surfaces so that if S is $(1 + \epsilon)$ -quasifuchsian surface that does not belong to the finite collection of totally geodesic surfaces, the following holds. Assume g is a metric on M with sectional curvature bounded above by -1 so that

- Σ is a totally geodesic hyperbolic surface in (M, g)
- There is a homotopy equivalence $\phi: M \to M$ so $\phi(\Sigma) = S$.

Then, g is isometric to g_{hyp} and S is homotopic to a totally geodesic surface in (M, g_{hyp}) .

As before we can take Σ to be the unique area-minimizing surface in its homotopy class and have principal curvatures as small as desired, by making ϵ small. We say that a surface Σ in M satisfies the *well-distribution property* if every point in $\tilde{M} \cong H^3$ is contained in a solid cube whose faces are contained in lifts of Σ to H^3 . It is a straightforward consequence of Theorem 1.1 that if ϵ is small enough and Σ is $(1 + \epsilon)$ -quasifuchsian, then Σ satisfies the well-distribution property unless it is totally geodesic. We also know by the Mozes-Shah theorem that at most finitely many closed totally geodesic surfaces fail to satisfy the well-distribution property.

There is a slightly stronger version of the well-distribution property called the *strong* well-distribution property [Low23][Definition 5.1] Using the fact that the Σ are asymptotically dense, it is not hard to check that Σ satisfies the strong well-distribution property provided Σ is $(1 + \epsilon)$ -quasifuchsian and not one of finitely many totally geodesic surfaces.

Assume that $h(\Sigma)$ is homotopic to a hyperbolic totally geodesic surface Σ' in N. The arguments in [Low23][Section 6.2] show that Σ' satisfies the well-distribution property if Σ satisfies the strong well-distribution property. From there [Low23][Theorem 1.1] implies that N has constant sectional curvature -1, and so by Mostow rigidity must be isometric to M.

6.2. The proof of Theorem 1.7 requires a different argument. We restate it here for convenience

Theorem 6.2. Let (M, g) be a negatively curved 3-manifold and $(\Sigma_n) \subset (M, g)$ be a sequence of asymptotically geodesic surfaces.

Suppose there is a diffeomorphism $\phi: M \to M$ so that $S_n := \phi(\Sigma_n)$ form a sequence of asymptotically geodesic surfaces for the hyperbolic metric g_{hyp} of M. Then, g is isometric to g_{hyp} .

Let Σ_n be the sequence of asymptotically geodesic surfaces in a closed negatively curved manifold M, and let $h: M \to (M, g_{hyp})$ be the homotopy equivalence from the assumptions of the theorem.

Let Σ'_n be the sequence of asymptotically geodesic minimal surfaces in (M, g_{hyp}) , obtained by taking the area-minimizing representatives of the homotopy classes $h(\Sigma'_n)$, which are unique for large enough n. In more detail, [Eps86][Equation 5.5] implies that since the $h(\Sigma_n)$ are homotopic to a sequence of asymptotically geodesic surfaces, their quasiconformal constants tend to 1, and then work by Seppi [Sep16] implies that area-minimizing representatives in their homotopy classes Σ'_n are asymptotically geodesic and unique (see also [HLS23].)

Since the Σ'_n are asymptotically Fuchsian and since it is not the case that all but finitely many are covering a fixed surface, we know that their tangent planes become dense in $Gr_2(M, g_{hyp})$ by Corollary 1.3. Choose tangent planes π_n to Σ'_n that converge, up to passing to a subsequence, to a tangent plane to M that contains a tangent vector with dense orbit under the geodesic flow.

The homotopy equivalence between (M,g) and (M,g_{hyp}) given by the assumptions of the theorem must be homotopic to a diffeomorphism by geometrization and the fact that every self homotopy equivalence of a closed hyperbolic manifold is homotopic to an isometry by Mostow rigidity: fix such a diffeomorphism $F:(M,g_{hyp}) \to (M,g)$ and choose a lift of F to an equivariant diffeomorphism $\tilde{F}:\mathbf{H}^3 \to (\tilde{M},\tilde{g})$, where we have identified the universal cover of (M,g_{hyp}) with \mathbf{H}^3 . Choose lifts $\tilde{\Sigma}'_n$ of Σ'_n to \mathbf{H}^3 whose intersection with a fixed fundamental domain for the action of $\pi_1(M)$ on \mathbf{H}^3 contain tangent planes that projects to π_n . After passing to a subsequence, we can assume that the $\tilde{\Sigma}'_n$ converge on compact subsets to a totally geodesic surface $\tilde{\Sigma}'$ that projects to a surface Σ' in (M,g_{hyp}) . Note that Σ' contains the tangent plane π , and thus Σ' has a tangent vector with dense orbit under the geodesic flow.

A choice of lift \tilde{F} of the diffeomorphism F to a map $(M, g_{hyp}) \to (M, g)$ between the universal covers and the choices of lifts $\tilde{\Sigma}'_n$ determine lifts $\tilde{\Sigma}_n$ of the Σ_n to (\tilde{M}, \tilde{g}) , that are at finite Hausdorff distance from the $\tilde{F}(\tilde{\Sigma}'_n)$. Using the fact that the $\tilde{\Sigma}_n$ are asymptotically geodesic, and so in particular have uniformly bounded second fundamental forms, and arguing like in [CMN22][Proposition 4.1], we can reason that, possibly after passing to a subsequence, the $\tilde{\Sigma}_n$ converge to a totally geodesic surface that we call $\tilde{\Sigma}$, and whose projection to (M, g) we call Σ . We claim that there is a totally geodesic surface that is dense in the 2-plane Grassmann bundle of (M, g). It then follows that every tangent 2-plane to M is tangent to a totally geodesic surface, which Cartan showed implies that M must have constant sectional curvature [Car28]. To finish the proof, it is therefore enough to show that there is a totally geodesic surface that is dense in the 2-plane Grassmann bundle of (M, g).

There is a homeomorphism $\Phi: \mathrm{UT}(M,g_{hyp}) \to \mathrm{UT}(M,g)$ that maps geodesics to geodesics (i.e., an orbit equivalence between the geodesic flow for g and the geodesic flow for g_{hyp}) [Gro00]. By how Φ is constructed, it is homotopic to the lift $\mathrm{UT}(M,g_{hyp}) \to \mathrm{UT}(M,g)$ of a diffeomorphism $(M,g_{hyp}) \to (M,g)$. By how we constructed Σ' and Σ , we know that, possibly after composing Φ with an element of the finite group of isometries of (M,g_{hyp}) , that Φ maps every unit tangent vector tangent to Σ' to a unit tangent vector tangent to Σ . Because Σ' contains a unit tangent vector with dense orbit under the geodesic flow, the same must be true of Σ . Choose a frame Π in the frame bundle of (M,g) that has dense orbit under the frame flow. This is possible because the frame flow of a closed negatively curved 3-manifold is ergodic [BG80].

Because Σ contains a vector with dense orbit under the geodesic flow, we can then choose a sequence of frames Π_n on Σ the initial vectors of which converge to the first vector of Π . Passing to a convergent subsequence of the Π_n so that they converge to some frame Π' , it will then be the case that the first two unit vectors in the frame Π' span a tangent plane that is a limit of tangent planes to Σ , and thus is itself tangent to a totally geodesic surface. Since Π and Π' share the same first vector and their second two vectors differ by a rotation in the plane orthogonal to the first vector, Π' also has dense orbit under the frame flow. The tangent plane spanned by the first two vectors of Π' is therefore tangent to a totally geodesic surface whose closure is all of $\operatorname{Gr}_2 M$, which finishes the proof.

7. Rigidity of totally umbilic surfaces

We give the proof of Theorem 1.10 from the introduction, restated here for convenience.

Theorem 7.1. Suppose that (M, g) is a closed negatively curved 3-manifold, and that it contains infinitely many distinct totally umbilic surfaces Σ_n as in Question 5. Suppose there is a homotopy equivalence $h: M \to M$ so that the $S_n := h(\Sigma_n)$ are homotopic to a sequence of asymptotically totally umbilic surfaces for a hyperbolic metric g_{hyp} on M. Then (M, g) must have constant curvature.

Let M be a closed negatively curved 3-manifold with sectional curvature at most -c, and let Σ_n be totally umbilic surfaces in M each with mean curvature constant and equal to $H_n < c$. Let h be a homotopy equivalence as in the statement of Theorem 1.10 between M and a closed hyperbolic 3-manifold (M, g_{hyp}) , so that the $h(\Sigma_n)$ are homotopic to a sequence of asymptotically totally umbilic surfaces $\hat{\Sigma}_n$. Because all totally umbilic surfaces in \mathbf{H}^3 with principal curvatures less than 1 are constant distance surfaces to totally geodesic planes in \mathbf{H}^3 , a simple contradiction compactness argument shows that the $\hat{\Sigma}_n$ are homotopic to a sequence Σ'_n of asymptotically geodesic surfaces in (M, g_{hyp}) . The tangent planes to the Σ'_n must be dense in $Gr_2(M)$ by Corollary 1.3, and consequently the same is true for the $\hat{\Sigma}_n$.

7.1. **Background on k-surfaces.** A *k-surface* is a surface for which the product of the principal curvatures, or extrinsic curvature, is constant and equal to *k*. They will be useful for us because totally umbilic surfaces are special cases of k-surfaces. Labourie initiated the study of the dynamical properties of the space of k-surfaces, presenting them as a higher-dimensional analogue of the geodesic flow when the ambient manifold is negatively curved [Lab99], [Lab05] (see [Lab02] for a survey.) We describe in this section results that will play the role of the geodesic orbit equivalence result used in Section 6.

If N is a negatively curved 3-manifold with sectional curvature at most -k, then the space of pointed k-surfaces in N (the space of k-surfaces together with a choice of basepoint) suitably topologized has the structure of a *lamination* \mathcal{L}_N , whose leaves are obtained by fixing a k-surface, and allowing the basepoint to vary [Lab99]. (While the k-surfaces corresponding to distinct leaves of this lamination may intersect inside N, they are disjoint in the phase space of pointed k-surfaces in N.) Labourie in the local case and Smith in general proved that this lamination is independent of the metric on N in the following sense: For any two N_1 and N_2 as above there is a leaf-preserving homeomorphism $\Phi_{\mathcal{L}}$ between \mathcal{L}_{N_1} and \mathcal{L}_{N_2} (see [Smi21] for precise statements.) We will need the following two facts about the leaf-preserving homeomorphism $\Phi_{\mathcal{L}}$, which readily follow from the construction and basic properties of the $\Phi_{\mathcal{L}}$, and which we write as propositions.

Proposition 7.2. Suppose that f is a homotopy equivalence between N_1 and N_2 . Then we can choose $\Phi_{\mathcal{L}}$ so that for every π_1 -injective k-surface Σ in N_1 , the k-surface corresponding to Σ under $\Phi_{\mathcal{L}}$ is homotopic to $f(\Sigma)$.

Proposition 7.3. Suppose that Σ_n is a sequence of k-surfaces in N_1 , and that there is a k-surface Σ in N_1 so that the following holds: there are lifts $\tilde{\Sigma}_n$ and $\tilde{\Sigma}$ to the universal cover of N_1 so that $\tilde{\Sigma}_n$ converges smoothly to $\tilde{\Sigma}$ on compact sets. Then the same statement holds for the k-surfaces Σ'_n and Σ' in N_2 that correspond respectively to the Σ_n and Σ under Φ_L .

We will also use recent work by Alvarez-Lowe-Smith [ALS22], that refined the existence of the leaf-preserving homeomorphisms $\Phi_{\mathcal{L}}$ as follows. Let (M, g_{hyp}) be a closed hyperbolic 3-manifold. Then for each 0 < k < 1, the unit tangent bundle to M has a natural foliation

 $\mathcal{F}_M(k)$ by totally umbilic surfaces with constant extrinsic curvature k, lifted by their unit normal vector fields (note that any totally umbilic surface has a canonical unit normal vector field, just by taking the unit vector field in the direction of the mean curvature vector.) This is because \mathbf{H}^3 has such a foliation that is invariant by isometries. The following theorem is a consequence of [ALS22][Theorem 2.1.3].

Theorem 7.4. For every negatively curved Riemannian 3-manifold N with sectional curvature at most -k the following holds. The unit tangent bundle UT(N) admits a foliation $\mathcal{F}_N(k)$ by k-surfaces lifted by their unit normal vectors. The foliation $\mathcal{F}_N(k)$ has the following property. Let M be a hyperbolic manifold diffeomorphic to N. Then there is a homeomorphism $\Phi: UT(M) \to UT(N)$ sending leaves of $\mathcal{F}_M(k)$ to leaves of $\mathcal{F}_N(k)$. Moreover, Φ can be chosen so that, for each leaf F of $\mathcal{F}_N(k)$, $\Phi(F)$ and $\Phi_L(F)$ are the same k-surface.

7.2. As in the Section 6, after passing to a subsequence we can find a dense immersed totally geodesic plane in (M, g_{hyp}) that lifts to a totally geodesic plane in \mathbf{H}^3 to which lifts of the Σ'_n converge. We can thus also find a totally umbilic plane $\hat{\Sigma}$ in (M, g_{hyp}) playing the same role for the $\hat{\Sigma}_n$: i.e., which has a lift to \mathbf{H}^3 to which lifts of the $\hat{\Sigma}_n$ converge (this totally umbilic plane is at constant distance to the totally geodesic plane of the previous sentence.)

After passing to a subsequence, we can assume that the H_n converge to some real number H. The extrinsic curvatures of the totally umbilic surfaces Σ_n in N consequently converge to H^2 . Let $\Phi: \mathrm{UT}(M) \to \mathrm{UT}(N)$ be the homeomorphism from Theorem 7.4 sending tangential lifts of k-surfaces in $\mathrm{UT}(M)$ to tangential lifts of k-surfaces in $\mathrm{UT}(N)$ for $k = H^2$. Then $\Phi(\hat{\Sigma})$ is dense in $\mathrm{UT}(N)$, and projects to a k-surface Σ in N for $k = H^2$. If Σ is totally umbilic, then every tangent plane to N is tangent to a totally umbilic surface. That M has constant curvature then follows from the main theorem of [LN71], which is the analogue for totally umbilic surfaces of the theorem by Cartan used in the previous section. It is therefore enough to prove that Σ is totally umbilic, which we will accomplish by showing every tangent plane to Σ is a limit of tangent planes to the Σ_n .

First assume that the extrinsic curvatures of the Σ_n are all equal to H^2 . Then it follows from Propositions 7.2 and 7.3 that lifts of $\hat{\Sigma}_n$ to the universal cover smoothly converge to a lift of $\hat{\Sigma}$ to the universal cover on compact sets, which establishes the claim.

In the general case that the H_n are allowed to vary, we let $\Sigma_n(H^2)$ be the unique k-surface in the homotopy class of Σ_n for $k=H^2$. Choose lifts $\tilde{\Sigma}_n(H^2)$ and $\tilde{\Sigma}_n$ of $\Sigma_n(H^2)$ and Σ_n to \tilde{N} , so that $\tilde{\Sigma}_n(H^2)$ and $\tilde{\Sigma}_n$ are at finite Hausdorff distance from each other, and intersect a fixed compact fundamental domain independent of n. Then if the Hausdorff distance between the tangential lifts of $\tilde{\Sigma}_n(H^2)$ and $\tilde{\Sigma}_n$ tends to zero as n tends to infinity, we will have reduced establishing the claim to the case that all Σ_n were H^2 surfaces and be able to conclude by the same argument as in the previous paragraph.

Therefore suppose that this fails, and that for some $\epsilon > 0$ it is the case that some fixed compact set K of the unit tangent bundle contains unit tangent vectors normal to $\tilde{\Sigma}_n(H^2) \cap K$

at a distance of at least $\epsilon > 0$ from $\tilde{\Sigma}_n \cap K$. Then after passing to subsequences the $\tilde{\Sigma}_n(H^2)$ and $\tilde{\Sigma}_n$ converge on compact sets to k-surfaces S_1 and S_2 for $k = H^2$ by [Smi24][Theorem 1.1.1, Remark 1.1.2]. But S_1 and S_2 have the same asymptotic boundary, and so $S_1 = S_2$ by the main results of [Lab99] (see also [Smi21]), which is a contradiction.

8. Asymptotically dense but not asymptotically geodesic minimal surfaces

In this section, we prove Theorem 1.11 from the introduction. We construct a sequence of essential surfaces built from pants as follows.

Recall the terminology from Section 5.2. For $\epsilon > 0$ and $R(\epsilon) > 0$ sufficiently large, let S^1_ϵ and S^2_ϵ be $(1 + O(\epsilon))$ -quasifuchsian closed connected surfaces built out of at least one copy of each pants in $\Pi_{\epsilon,R}$, all glued via (ϵ,R) -good gluings. For a fixed small θ , we wish to build a surface $S_{\epsilon,\theta}$, by cutting S^1_ϵ and S^2_ϵ along a cuff $\gamma \in \Gamma_{\epsilon,R}$ and regluing them at an angle approximately equal to θ .

Precisely, fix a cuff $\gamma \in \Gamma_{\epsilon,R}$. By the equidistribution of feet, there are pants $\pi_1^- \in \Pi_{\epsilon,R}^-(\gamma)$ and $\pi_2^- \in \Pi_{\epsilon,R}^-(\gamma)$, lying respectively on S^1 and S^2 so that

$$|\operatorname{ft} \pi_1^- - \operatorname{ft} \pi_2^- - i\theta| < \frac{\epsilon}{R}.$$

We also know there are $\pi_1^+ \in \Pi_{\epsilon,R}^+(\gamma)$ and $\pi_2^+ \in \Pi_{\epsilon,R}^+(\gamma)$, lying respectively on S^1 and S^2 that satisfy

$$|\operatorname{ft} \pi_1^- - \tau(\operatorname{ft} \pi_1^+)| < \frac{\epsilon}{R} \quad \text{and} \quad |\operatorname{ft} \pi_2^- - \tau(\operatorname{ft} \pi_2^+)| < \frac{\epsilon}{R},$$

where $\tau: N^1(\sqrt{\gamma}) \to N^1(\sqrt{\gamma})$ is the map $\tau: x \to x+1+i\pi$. We obtain our surface $S_{\epsilon,\theta}$ by cutting both S^1 and S^2 along γ and regluing them by gluing π_1^- to π_2^+ and π_1^+ to π_2^- . It follows from [KM12a] that $S_{\epsilon,\theta}$ is $K(\theta)$ -quasifuchsian.

We form a good matching of (ϵ, R) good pants as before for $\epsilon \to 0$, $R \to \infty$, except that we choose one pair of pants to glue together at a small angle θ along their cuff, for θ independent of n. Denote the sequence of surfaces thus obtained by $S_n(\theta)$. Choose a minimal surface $\Sigma_n(\theta)$ in the homotopy class of $S_n(\theta)$.

Choose a Dirichlet fundamental domain for the action of $\pi_1(M)$ on \mathbf{H}^3 , and lift the closed geodesic at which pants in $S_n(\theta)$ are glued at a definite angle to a geodesic $\gamma_n(\theta)$ in \mathbf{H}^3 that intersects Δ and that is contained in a lift $\tilde{S}_n(\theta)$ of $S_n(\theta)$. The *width* of the convex hull of a quasicircle in $\partial_{\infty}(\mathbf{H}^3)$ is the supremal distance between points in different components of its boundary. We know that the width of the convex core of the limit set of $\tilde{S}_n(\theta)$ is at least some positive constant just depending on θ . This implies that the K for which $S_n(\theta)$ is K-quasiconformal is uniformly bounded away from 1 (see e.g. the proof of the main theorem of [Sep16], which implies a bound for the width of the convex hull in terms of

the quasiconformal constant.) Work by Epstein [Eps86][Equation 5.5] then implies that the minimal surface $\Sigma_n(\theta)$ must have principal curvatures uniformly bounded away from 1 by a constant that depends only on θ .

On the other hand, choose a sequence of points $p_n(\theta)$ on $S_n(\theta)$ so that:

- (1) The tangent planes Π_n to $S_n(\theta)$ are well-defined and converge to a plane $\Pi \in Gr_2(M)$ tangent to a dense totally geodesic plane in $Gr_2(M)$.
- (2) The distance on $S_n(\theta)$ between $p_n(\theta)$ and $\gamma_n(\theta)$ tends to infinity.

Choose lifts $\tilde{S}_n(\theta)$ of $S_n(\theta)$ to \mathbf{H}^3 containing lifts $\tilde{p}_n(\theta)$ of $p_n(\theta)$ that are contained in Δ , and let $\tilde{\Sigma}_n(\theta)$ be the corresponding lifts of $\Sigma_n(\theta)$ to \mathbf{H}^3 . Then by the second property above $\tilde{S}_n(\theta)$ converges to a totally geodesic plane on compact subsets of \mathbf{H}^3 . Therefore the convex hull of $\tilde{S}_n(\theta)$ converges to a totally geodesic plane on compact subsets of \mathbf{H}^3 . Since $\tilde{\Sigma}_n(\theta)$ is a minimal surface, it is contained in the convex hull, and so it must also converge to a totally geodesic plane. It follows that the closure of $\Sigma_n(\theta)$ in $Gr_2(M)$ contains the closure of the totally geodesic plane tangent to Π in $Gr_2(M)$, and so its closure is all of $Gr_2(M)$.

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